

Extremal characteristics of conditional models

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Abstract

Conditionally specified models are often used to model complex multivariate data. Such models assume implicit structures on the extremes. So far, there exist no methodology for calculating extremal characteristics of conditional models as the copula and marginals are not expressed in closed forms. We consider bivariate conditional models that specify the distribution of X and the distribution of Y conditional on X . We provide tools to calculate implicit assumptions on the extremes of this class of models. In particular, these tools allow us to approximate the distribution of the tail of Y and the coefficient of asymptotic independence η in closed forms. We apply these methods to a widely used conditional model for wave height and wave period. Moreover, we introduce a new condition on the parameter space for the conditional extremes model of [Heffernan and Tawn \(2004\)](#), and we prove that there exist models that asymptotically follow the same conditional representation but have different η .

Keywords: Multivariate Extremes, Conditional Extremes, Laplace Approximation

1 Introduction

Extreme value theory is a topic of growing interest because of its many important applications in for example risk management (Embrechts et al., 1999) or ocean engineering (Castillo et al., 2005). For instance, in the design or assessment of offshore facilities it is crucial to understand the distribution of extreme sea states. Such extreme sea states are quantified in terms of extreme wave heights, wave periods possibly associated with resonant frequencies, and extreme wind speeds. In risk management, it is important to identify which stocks are likely to suffer extreme losses simultaneously, and to which extent this might happen. In general, we need to use well-established extreme value methods to model such events. Traditionally, such multivariate extreme value methods are composed of marginal models and a dependence copula, each having parametric forms for the tails.

In other areas of statistics, however, it is common to use conditional models for multidimensional data. Intuitively, this is the most sensible approach. We observe X that partially explains Y . So, we define a model for X and a model for Y conditional on X . There exist many examples in the literature of models within this conditional framework with applications in extremes, e.g., the conditional extreme value model (Heffernan and Tawn, 2004; Fougères and Soulier, 2012), the Weibull-log normal distribution (Haver and Winterstein, 2009, henceforth the Haver-Winterstein distribution), and hierarchical models (Eastoe, 2019). Although conditional models are easy to interpret, it can be rather difficult to study the extremes of both Y and (X, Y) within this class. Recently, Engelke and Hitz (2020) developed graphical models for extremes. However, we do not know of any literature that links existing conditional models directly to extremal dependence measures.

There are two extremal dependence measures that are key in identifying and measuring the degree of asymptotic dependence or asymptotic independence (Coles et al., 1999). Identifying the correct asymptotic dependence class is important since extrapolation of models from different classes is different. To define asymptotic dependence, we first define $\chi \in [0, 1]$, with

$$\chi := \lim_{p \uparrow 1} \chi(p) := \lim_{p \uparrow 1} \mathbb{P}\{Y > F_Y^{-1}(p) \mid X > F_X^{-1}(p)\}, \quad (1)$$

where F_X and F_Y denote the marginal distribution functions of X and Y . We say that these random variables are asymptotically dependent if $\chi > 0$, i.e., when the joint probability that both random variables are large is of the same magnitude as when one is large. If the coefficient of asymptotic dependence $\chi = 0$, we say that the variables are asymptotically independent. In this case, χ does not give us information on the level of asymptotic independence. So, we additionally define the coefficient of asymptotic independence $\eta \in (0, 1]$ (Ledford and Tawn, 1996). This coefficient describes the rate of decay to zero of the joint exceedance probability $\mathbb{P}\{X > F_X^{-1}(p), Y > F_Y^{-1}(p)\}$ as p tends

to 1. More specifically, η is defined to satisfy

$$\mathbb{P}\{X > F_X^{-1}[F_E(u)], Y > F_Y^{-1}[F_E(u)]\} \sim \mathcal{L}(e^u) e^{-u/\eta} \quad (2)$$

as $u \rightarrow \infty$, where $F_E(u) = 1 - \exp(-u)$ is the distribution function of a standard exponential, and where \mathcal{L} is a slowly varying function. Here, we write $f(x) \sim g(x)$ as $x \rightarrow \infty$ when $f(x)/g(x) \rightarrow 1$ as $x \rightarrow \infty$. We rewrite definition (2) as

$$\eta := \lim_{p \uparrow 1} \eta(p) := \lim_{p \uparrow 1} \frac{\log(1-p)}{\log[(1-p)\chi(p)]}. \quad (3)$$

If the variables are asymptotically dependent, then $\eta = 1$; if the variables are asymptotically independent, then $\eta \in (0, 1)$ or $\eta = 1$ and $\mathcal{L}(u) \rightarrow 0$ as $u \rightarrow \infty$.

Evaluating χ for a bivariate random variable (X, Y) is relatively straightforward. First, define for each $z \in \mathbb{R}$,

$$\overline{H}(z) := \lim_{p \uparrow 1} \mathbb{P}\left(\log\left(\frac{1 - F_X(X)}{1 - F_Y(Y)}\right) > z \mid F_X(X) > p\right).$$

Although this formulation looks complex, it is simply an analogue of the spectral measure (Engelke and Hitz, 2020) in Fréchet margins but here it is expressed as a representation in exponential margins, see Section 4. We then apply the dominated convergence theorem to get

$$\chi = \int_0^\infty \overline{H}(-x) e^{-x} dx.$$

In particular, $\chi > 0$ if and only if $\lim_{z \rightarrow -\infty} \overline{H}(z) > 0$.

Additionally calculating η is straightforward for distributions when the joint distribution function is specified parametrically, e.g., a bivariate extreme value distribution (Ledford and Tawn, 1996), or when the joint density function is specified parametrically (Nolde and Wadsworth, 2021), e.g., a multivariate normal distribution. In this paper, we consider models specified within the conditional framework. For these cases, it is hard to calculate η analytically, and numerical estimation can be difficult since convergence of $\eta(p)$ to η can be exceptionally slow. We set up methodology to calculate η in closed form within this framework and demonstrate the techniques on two widely used examples specified below. We support these limiting results using numerical integration.

First, we consider the model described in Haver and Winterstein (2009), used to explain the dependence between extreme significant wave height and their associated wave periods. Secondly, we investigate the model of Heffernan and Tawn (2004). This is a conditional model which describes the distribution of $Y \mid X$ for large X , where both X and Y are on standard margins. As the Heffernan-Tawn model focusses on normalising the distribution of $Y \mid X = x$ as $x \rightarrow \infty$ to give a non-degenerate limit, it asymptotically focusses on a different

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aspect of the joint distribution to the events which determine η , i.e., $\{X > x, Y > x\}$ as $x \rightarrow \infty$, when the variables are asymptotically independent. As a consequence, it seems reasonable to expect that the upper tail of $Y|X = x$ for large x does not give η . We will show by giving an example that there exist distributions that share the same Heffernan-Tawn normalization but do not share the same η . More theoretical examples, like $Y | X := X^\beta Z$ and $Y | X := |Z|^{|X|}$ where Z is some random variable independent of X , can be found in the Ph.D. thesis of [Tendijck \(2023\)](#).

The layout of the article is as follows. In [Section 2](#), we demonstrate novel techniques for calculating the coefficient of asymptotic independence η and illustrate the techniques with some examples. In [Sections 3](#) and [4](#), we apply these techniques to the Haver-Winterstein model and the Heffernan-Tawn model, respectively. Proofs are found in the Appendix and Supplementary Material.

2 Methodology

2.1 Motivation

We aim to investigate the extremal properties of the bivariate distribution of (X, Y) , for which the distribution of X and the distribution of $Y | X$ are specified. In particular, we aim to investigate the tail of the distribution of Y and joint extremes of X and Y via the coefficient of asymptotic independence η . Deriving such extremal quantities in closed form within this class is not trivial. In this section, we provide a set of tools, derived from the Laplace approximation, to calculate such properties for any conditional model.

First, we consider the tail of the distribution of Y . Because the distributions of X and $Y | X$ are specified, it is natural to write

$$1 - F_Y(y) := \mathbb{P}(Y > y) = \int_{-\infty}^{\infty} \mathbb{P}(Y > y | X = x) f_X(x) dx,$$

where f_X is the density of X . In general, this integral is analytically intractable. In [Section 2.2](#), we present the tools with which we can derive the asymptotic properties of this integral as y tends to the upper end point of the distribution of Y .

To derive the coefficient of asymptotic independence, we additionally need the inverse distribution $F_Y^{-1}(p)$ for values of p close to 1, and

$$\mathbb{P}(X > F_X^{-1}(p), Y > F_Y^{-1}(p)) = \int_{F_X^{-1}(p)}^{\infty} \mathbb{P}(Y > F_Y^{-1}(p) | X = x) f_X(x) dx.$$

This integral is also intractable in general; the tools from [Section 2.2](#) can again be applied to derive the asymptotic decay to 0 as p tends to 1.

2.2 Extension to the Laplace approximation

Here we present our theory to calculate asymptotic rates of decay of integrals, that can be used to compute extremal properties, such as η , of conditional models. We first recall the Laplace approximation, a technique commonly used in Bayesian inference for approximating intractable integrals. This asymptotic approximation forms the basis of our main result. We then state that result, and illustrate key differences with the Laplace approximation by comparing examples.

Proposition 1 (Laplace approximation) *Let $a < b$. Suppose $g : [a, b] \rightarrow \mathbb{R}$ is twice continuously differentiable and assume there exists a unique $x^* \in (a, b)$ such that $g(x^*) = \max_{x \in [a, b]} g(x)$ and $g''(x^*) < 0$. Then*

$$\int_a^b e^{ng(x) - ng(x^*)} dx \cdot \sqrt{n(-g''(x^*))} \sim \sqrt{2\pi}$$

as $n \rightarrow \infty$.

The main disadvantage of the Laplace approximation is that it can only be used to approximate integrals where the integrands are of the form $f(x)^n$, where $f(x) = e^{g(x)}$ is a positive function. However, we are interested in calculating integrals with integrand $f_n(x) = e^{g_n(x)}$, for some sequence of functions $\{g_n\}_{n \in \mathbb{N}}$. Now we extend the Laplace approximation under the assumptions that: (i) the analogue x_n^* of x^* is allowed to depend on n ; (ii) x_n^* can be equal to either a or b ; (iii) $g_n''(x_n^*)$ does not need to be negative.

Proposition 2 *Let $I \subseteq \mathbb{R}$ be connected with non-zero Lebesgue mass, $k_0 \geq 1$ an integer, and $g_n \in C^{k_0}(I)$ a sequence of real-valued (at least) k_0 -times continuously differentiable functions defined on I . For $1 \leq i \leq k_0$, we define $g_n^{(i)}$ as the i th derivative of g_n . We assume that for all $n \in \mathbb{N}$, there exists a unique $x_n^* \in I$ such that $g_n(x_n^*) > g_n(x)$ for all $x \in I \setminus \{x_n^*\}$. Moreover, we assume that k_0 is the smallest integer such that $g_n^{(k_0)}(x_n^*) < 0$ and $\lim_{n \rightarrow \infty} g_n^{(i)}(x_n^*) [-g_n^{(k_0)}(x_n^*)]^{-i/k_0} = 0$ for all $1 \leq i < k_0$. Additionally, assume that there exists a $\delta > 0$ for which there exists an $\varepsilon > 0$ such that for all $|x| < \delta$*

$$\lim_{n \rightarrow \infty} \frac{g_n^{(k_0)} \left\{ x_n^* + x \left[-g_n^{(k_0)}(x_n^*) \right]^{-\frac{1}{k_0}} \right\}}{g_n^{(k_0)}(x_n^*)} < 1 + \varepsilon.$$

Then, for $n > N$, there exists a constant $C_1 > 0$ such that

$$\int_I e^{g_n(x) - g_n(x_n^*)} dx \cdot \left[-g_n^{(k_0)}(x_n^*) \right]^{\frac{1}{k_0}} \geq C_1.$$

The proof of Proposition 2 can be found in Appendix A. One disadvantage of our extension is that it only gives an asymptotic lower bound. In many practical applications, an upper bound can be found directly using inequalities like that in equation (8).

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Functions for which Proposition 2 is applicable include functions g_n with a single mode x_n^* that are approximated well with a Taylor expansion of some order on a large enough neighbourhood of the mode. For example, for $g_n(x) = -|x|^p$ with $p \in \mathbb{R}$, the proposition is applicable if and only if $p \in \mathbb{Z}$. We specify further that the first set of assumptions ensures that the k_0 th order Taylor approximation of g_n around x_n^* has at most two significant terms (the 0th and the k_0 th term) by setting a limit on the size of the i th terms in this Taylor approximation, where $1 \leq i \leq k_0 - 1$. The second set of assumptions defines if the Taylor approximation is good enough on a neighbourhood of x_n^* , see the second example in Section 2.3

2.3 Examples

We demonstrate the use of Proposition 2 in three cases. Firstly, let $g_n(x) = -nx^m$ for $n \in \mathbb{N}$, $m \in \mathbb{Z}_{\geq 1}$ and $I = [0, \infty)$. It is then valid to apply Proposition 2 with $x_n^* = 0$ and $k_0 = m$. Applying the proposition yields a constant $C_1 > 0$ such that for sufficiently large n ,

$$n^{\frac{1}{m}} \int_0^{\infty} e^{-nx^m} dx \geq C_1.$$

This lower bound is tight for each $m \geq 1$. We verify this by using the variable transformation $y = nx^m$ to give

$$n^{\frac{1}{m}} \int_0^{\infty} e^{-nx^m} dx = \frac{1}{m} \int_0^{\infty} y^{\frac{1}{m}-1} e^{-y} dy = \Gamma\left(\frac{1}{m} + 1\right).$$

After recognizing that the integral over $[0, \infty)$ is equal to half of the integral over \mathbb{R} , we see that Proposition 1 is applicable only when $m = 2$. In this case, Proposition 1 additionally gives as $n \rightarrow \infty$

$$\int_0^{\infty} e^{-nx^2} dx = \frac{1}{2} \int_{-\infty}^{\infty} e^{-nx^2} dx \sim \frac{\sqrt{\pi}}{2\sqrt{n}}.$$

Secondly, let $g_n(x) = -x - nx^2$ and $I = [0, \infty)$. Now Proposition 1 is not applicable since no function $g(x)$ exists for which $g_n(x) = ng(x)$ holds. Note that Proposition 2 is also not applicable with $k_0 = 1$, since x_n^* has to be equal to 0 and for $x \neq 0$

$$\lim_{n \rightarrow \infty} \frac{g'_n(0 + x \cdot n)}{g'_n(0)} = \lim_{n \rightarrow \infty} 1 + 2n^2x = \infty,$$

contradicting one of the assumptions. Proposition 2 is applicable with $k_0 = 2$, yielding a constant $C_2 > 0$ such that for sufficiently large n ,

$$\sqrt{n} \int_{-\infty}^{\infty} e^{-x-nx^2} dx \geq C_2.$$

Similar to our first example, this lower bound is tight since we can also directly calculate as $n \rightarrow \infty$

$$\sqrt{n} \int_{-\infty}^{\infty} e^{-x-nx^2} dx = \sqrt{n} \int_{-\infty}^{\infty} e^{-n(x+\frac{1}{2n})^2 + \frac{1}{4n}} dx \sim \sqrt{\pi}.$$

Finally, let $\alpha_n > 0$, $\beta_n > 0$ for $n \in \mathbb{N}$ and assume $\liminf \alpha_n > 0$. Define $g_n(x) = \alpha_n \log x - \beta_n x$. Using an argument similar to that in the second example, we see that Proposition 1 is not applicable. However Proposition 2 is applicable with $k_0 = 2$, yielding a constant $C_3 > 0$ such that for sufficiently large n ,

$$\alpha_n^{-\alpha_n - \frac{1}{2}} \beta_n^{\alpha_n + 1} e^{\alpha_n} \int_0^{\infty} x^{\alpha_n} e^{-\beta_n x} dx \geq C_3.$$

This bound is also tight, which can be seen from recognizing the density of a gamma distribution in the expression above, and applying limit results for the gamma function.

3 Haver-Winterstein model

Haver and Winterstein (2009) introduce the Haver-Winterstein (HW) distribution for significant wave height H_S and wave period T_p in the North Sea. Their model is set up in the conditional framework: they specify a class of distributions for H_S and a class of distributions for $T_p | H_S$. Variations of this approach have been widely applied in ocean engineering with over 150 citations, 25 of which correspond to 2021, see for example Drago et al. (2013). However we are not aware of any literature quantifying χ and η in closed form for the HW distribution; we now show how to calculate these.

The marginal distribution of the HW is formulated as

$$f_X(x) = \begin{cases} \frac{1}{\sqrt{2\pi\alpha x}} \exp\left\{-\frac{(\log x - \theta)^2}{2\alpha^2}\right\}, & \text{for } 0 < x \leq u, \\ \frac{k}{\lambda^k} x^{k-1} \exp\left\{-\left(\frac{x}{\lambda}\right)^k\right\}, & \text{for } x > u. \end{cases} \quad (4)$$

where $u, \alpha, k, \lambda > 0$ and $\theta \in \mathbb{R}$. In particular, the parameters are constrained such that f_X is continuous at u and integrates to 1. Secondly, they take $Y | X$ to be conditionally log-normal

$$f_{Y|X}(y | x) = \frac{1}{\sqrt{2\pi}\sigma(x)y} \exp\left\{-\frac{(\log y - \mu(x))^2}{2\sigma(x)^2}\right\}, \quad \text{for } x, y > 0, \quad (5)$$

where $\mu(x) := \mu_0 + \mu_1 x^{\mu_2}$ and $\sigma(x) := [\sigma_0 + \sigma_1 \exp(-\sigma_2 x)]^{1/2}$ with $\mu_0 \in \mathbb{R}$, $\mu_1, \mu_2, \sigma_0, \sigma_1, \sigma_2 > 0$.

Model parameter estimates (Haver and Winterstein, 2009) from data observed in the northern North Sea are given in the Supplementary Material. For ease of presentation, we make two assumptions about the parameter space of the HW distribution that are consistent with parameter estimates

$(\hat{\mu}_2, \hat{k}) = (0.225, 1.55)$ from [Haver and Winterstein \(2009\)](#). Specifically, we make the following restrictions: $0 < \mu_2 < 0.5$ and $2\mu_2 < k$. These assumptions reduce the number of cases to be considered significantly whilst including realistic domains for the parameters as considered by practitioners.

We now show how to use [Proposition 2](#) to calculate the extremal dependence measures χ and η for the bivariate random vector (X, Y) distributed according to the HW distribution in the restricted parameter space. Calculation of η is split into two steps. In the first step, we calculate the distribution function F_Y of Y and in the second we evaluate the rate of decay of joint probabilities $\mathbb{P}\{X > F_X^{-1}[F_E(u)], Y > F_Y^{-1}[F_E(u)]\}$ as u tends to infinity.

We have

$$\mathbb{P}(Y > y) = \int_0^\infty \mathbb{P}(Y > y \mid X = x) f_X(x) dx = \int_0^\infty \bar{\Phi} \left(\frac{\log y - \mu(x)}{\sigma(x)} \right) f_X(x) dx, \quad (6)$$

where $\bar{\Phi}$ is the survival function of a standard Gaussian. This integral is analytically intractable but we can calculate its limiting leading order behaviour in closed form. [Proposition 2](#) gives a lower bound and an upper bound of the same order as the lower bound is then found directly. For ease of notation, we denote the integrand by

$$g_y(x) := \bar{\Phi} \left(\frac{\log y - \mu(x)}{\sigma(x)} \right) f_X(x) \quad (7)$$

for $x > 0$. In [Figure 1](#), we plot g_y for various values of y . From the figure, we note that g_y has two local maxima for sufficiently large y . These are x_y^* , which converges to zero, and x_y^{**} , which diverges to infinity. This observation implies that we cannot apply [Proposition 2](#) directly in this case. We therefore proceed as follows: (i) calculate x_y^* and x_y^{**} ; (ii) partition the interval of integration into intervals I_1 and I_2 , where $x_y^* \in I_1$ and $x_y^{**} \in I_2$, such that the conditions of [Proposition 2](#) hold for both intervals, and then apply the proposition on each interval; (iii) combine the two lower bounds found to get a lower bound for integral [\(6\)](#); (iv) derive a limiting upper bound for integral [\(6\)](#) of the same order as the lower bound.

In the [Supplementary Material](#), we derive that as $y \rightarrow \infty$

$$x_y^* \sim \left(\frac{\sigma_1 \sigma_2 \cdot \log y}{2\mu_1 \mu_2 (\sigma_0 + \sigma_1)} \right)^{-\frac{1}{1-\mu_2}} \quad \text{and} \quad x_y^{**} \sim \left(\frac{\lambda^k \mu_1 \mu_2 \cdot \log y}{k \sigma_0} \right)^{\frac{1}{k-\mu_2}},$$

where in the calculation of x_y^* we use $0 < \mu_2 < 0.5$. From [Figure 1](#), we recognize that $g_y(x_y^*) > g_y(x_y^{**})$ as $y \rightarrow \infty$. We show that this holds analytically in the [Supplementary Material](#) when $2\mu_2 < k$. We now apply [Proposition 2](#) and find that $k_0 = 2$ is appropriate. The proposition then gives a lower bound for

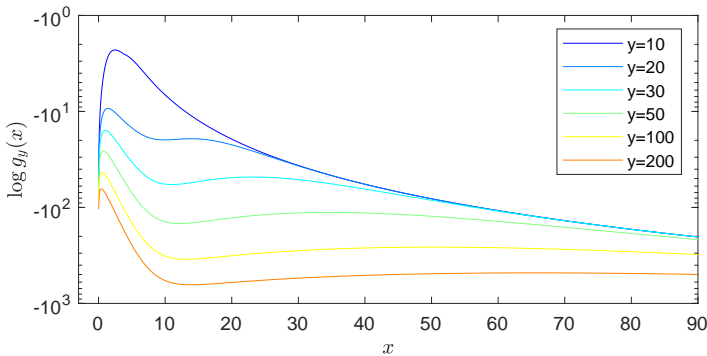


Figure 1 The function $\log g_y$ from equation (7) for $y = 10, 20, 30, 40, 50, 100$ with parameters as reported in [Haver and Winterstein \(2009\)](#), see Supplementary Material.

integral (6) around x_y^* as $y \rightarrow \infty$ of

$$\mathbb{P}(Y > y) \geq \exp \left\{ -\frac{\log^2 y}{2(\sigma_0 + \sigma_1)} + O(\log y) \right\}.$$

Finally, since $g_y(x_y^*) > g_y(x_y^{**})$, it is straightforward to show as $y \rightarrow \infty$ that

$$\mathbb{P}(Y > y) \leq \exp \left\{ -\frac{\log^2 y}{2(\sigma_0 + \sigma_1)} + O(\log y) \right\}$$

using the inequality

$$\mathbb{P}(Y > y \mid X = x) f_X(x) \leq g_y(x_y^*) \mathbb{1}\{x \in [0, x_y^{**}]\} + f_X(x) \mathbb{1}\{x > x_y^{**}\}. \quad (8)$$

We now can calculate η and show that $\chi = 0$. To that end, we first need to calculate the inverse probability integral transform, transforming Y to standard exponential margins; i.e., we need $F_Y^{-1}[F_E(u)]$. Next, we need to evaluate the asymptotic behaviour of $\mathbb{P}\{Y > F_Y^{-1}[F_E(u)], X > F_X^{-1}[F_E(u)]\}$ as $u \rightarrow \infty$. To evaluate $F_Y^{-1} \circ F_E$, we first calculate for $y \rightarrow \infty$

$$F_E^{-1}(F_Y(y)) = -\log(1 - F_Y(y)) = \frac{\log^2 y}{2(\sigma_0 + \sigma_1)} + O(\log y).$$

We invert this expression by solving $F_E^{-1}(F_Y(y)) = u$ for $\log y$. This yields $\log y = \sqrt{2(\sigma_0 + \sigma_1)u} + O(1)$ as $u \rightarrow \infty$. We can now write down an asymptotic

expression for $\chi(u)$ as $u \rightarrow \infty$

$$\begin{aligned} \chi(u) &:= \mathbb{P} \left\{ F_E^{-1} [F_Y(Y)] > u, F_E^{-1} [F_X(X)] > u \right\} \\ &= \mathbb{P} \left\{ \log Y > \sqrt{2(\sigma_0 + \sigma_1)u} + O(1), (X/\lambda)^k > u \right\} \\ &= \int_{\lambda u^{1/k}}^{\infty} \bar{\Phi} \left(\frac{\sqrt{2\sigma_0 + \sigma_1}u + O(1) - \mu(x)}{\sigma(x)} \mid X = x \right) \cdot \frac{kx^{k-1}}{\lambda^k} \exp \left\{ - \left(\frac{x}{\lambda} \right)^k \right\} dx. \end{aligned}$$

In the Supplementary Material, we show that Proposition 2 is applicable for this integral with $k_0 = 1$ and $x_u^* = \lambda u^{1/k}$. Moreover, we derive directly an upper bound of the same order, obtaining

$$\chi(u) = \exp \left\{ - \left(2 + \frac{\sigma_1}{\sigma_0} \right) u + O \left(u^{1/2 + \mu_2/k} \right) \right\}$$

as $u \rightarrow \infty$. Hence, $\chi = 0$ and

$$\eta = \left(2 + \frac{\sigma_1}{\sigma_0} \right)^{-1}.$$

In particular, for the parameter estimates from [Haver and Winterstein \(2009\)](#), the value of $\eta \in (0, 1/2)$ implies that the distribution exhibits negative asymptotic independence ([Ledford and Tawn, 1996](#)). This contrasts with the positive correlation of the Haver-Winterstein distribution, which might lead practitioners to assume falsely that the positive correlation also exists in the extremes of the Haver-Winterstein model; this is far from the truth.

What we learn from our work is not necessarily that the Haver-Winterstein model should not be used - we can derive this conclusion in many simpler ways than with this paper. Instead, we can use this example to understand how a conditional model makes complex assumptions on the dependence structure: imposing a positive correlation overall but a highly negative correlation in the extremes.

4 Heffernan-Tawn model

In multivariate extreme value theory, the conditional extreme value model of [Heffernan and Tawn \(2004\)](#), henceforth denoted the HT model, is widely studied and applied to extrapolate multivariate data. The HT model has been cited over 600 times, and is applied e.g. in oceanography ([Ross et al., 2020](#)), finance ([Hilal et al., 2011](#)), and spatio-temporal extremes ([Simpson and Wadsworth, 2021](#)). The HT model is a limit model and its form is motivated by derived limiting forms from numerous theoretical examples.

Let (X, Y) be a bivariate random variable with standard Laplace margins ([Keef et al., 2013](#)) and assume that its joint density exists. Next, assume there

exist parameters $\alpha \in [-1, 1]$, $\beta < 1$ and a non-degenerate distribution function H such that for $x > 0$, and for all $z \in \mathbb{R}$ the following limit

$$H(z) = \lim_{x \rightarrow \infty} \mathbb{P} \left(\frac{Y - \alpha x}{x^\beta} \leq z \mid X = x \right) \quad (9)$$

exists. This implies, according to l'Hopital's rule, that

$$\lim_{u \rightarrow \infty} \mathbb{P} \left(\frac{Y - \alpha X}{X^\beta} \leq z, X - u > x \mid X > u \right) = H(z) \exp(-x). \quad (10)$$

The latter in turn has the interpretation that as u tends to infinity, $(Y - \alpha X)X^{-\beta}$ and $(X - u)$ are independent conditional on $X > u$, and are distributed as H and a standard exponential, respectively. As is common practice in extreme value theory, the limit results are assumed to hold above some high threshold. So here, the HT model assumes that the corresponding limiting family in (9) holds exactly at a finite level u and beyond.

Now, if we additionally assume that a $u > 0$ exists such that for all $x > u$

$$\mathbb{P}(Y > y \mid X = x) = \overline{H} \left(\frac{y - \alpha x}{x^\beta} \right) \quad (11)$$

holds for all $y \in \mathbb{R}$ where $\overline{H} = 1 - H$ is some non-degenerate survival function. Then, we say that (X, Y) is modelled with the exact version of the HT model.

In this case study, we assume that (X, Y) is modelled with the exact version of the HT model with the additional assumption that $\alpha, \beta \in [0, 1)$. We consider two cases for H , corresponding to finite and infinite upper end points. If H has a finite upper end point z^H , calculations for η are trivial. Indeed, when $X = x$, Y cannot be larger than $\alpha x + x^\beta z^H$. Thus, as $u \rightarrow \infty$, $Y > u$ implies $X > u/\alpha + o(u)$. So, as $u \rightarrow \infty$

$$\begin{aligned} \mathbb{P}(X > u, Y > u) &\sim \mathbb{P} \{X > u, X > u/\alpha + O(u^\beta)\} \\ &\sim \mathbb{P} \{X > u/\alpha + O(u^\beta)\} \\ &= \exp \{-u/\alpha + O(u^\beta)\}. \end{aligned}$$

Therefore, $\eta = \alpha$ when $\alpha > 0$ and otherwise does not exist.

Now assume that H has an infinite upper end point. To make calculations tractable, we parameterise \overline{H} as

$$\overline{H}(z) = \exp \{-\gamma z^\delta + o(z^\delta)\} \mathbb{1}\{z > 0\} + \mathbb{1}\{z \leq 0\} \quad (12)$$

for $\gamma > 0$, $\delta \geq 1$. For simplicity, we do not consider potential negative arguments for \overline{H} since the precise form of its lower tail is not relevant to the current

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α	β	γ	δ	η
(0, 1)	[0, 1)	(0, ∞)	$((1 - \beta)^{-1}, \infty)$	α
(0, 1)	(0, 1)	(0, ∞)	$(1 - \beta)^{-1}$	$\left(\frac{\gamma(1 - \alpha c)^\delta}{c^{\delta - 1}} + c\right)^{-1}$
(0, 1)	0	$(1/\alpha, \infty)$	1	α
(0, 1)	0	$(0, 1/\alpha]$	1	$1/(\gamma + 1 - \gamma\alpha)$
0	(0, 1)	(0, ∞)	$((1 - \beta)^{-1}, \infty)$	Not defined
0	(0, 1)	$(0, (1 - \beta)/\beta]$	$(1 - \beta)^{-1}$	$1/(\gamma + 1)$
0	(0, 1)	$[(1 - \beta)/\beta, \infty)$	$(1 - \beta)^{-1}$	$\gamma^{-1/\delta}(\delta - 1)^{1 - 1/\delta}/\delta$

Table 1 Values of η for model (11) with \bar{H} as in (12) for different ranges of parameter combinations, where $c = \max\{1, c_0\} \in [1, 1/\alpha]$ for c_0 given in equation (13).

work. Parameterisation (12) covers most non-trivial light-tailed cases for the upper tail including Gaussian, Weibull and exponential tails; see examples in [Heffernan and Tawn \(2004\)](#). It is also the tail model of the delta-Laplace (generalised Gaussian) distribution used in spatial conditional extremes model, e.g., [Shooter et al. \(2021\)](#). Moreover if the tail of \bar{H} is heavier than that of the exponential, Y cannot possibly follow a standard Laplace distribution. This links to the restriction $\delta \geq 1$. For illustration, we set $o(z^\delta) = 0$ in equation (12). The resulting Weibull survival function is a suitable choice for \bar{H} , since it has an extreme value tail index of 0, but a varying tail thickness controlled by δ .

Proposition 3 *If (X, Y) follows distribution (11) with H as in (12) with $o(z^\delta) = 0$, then $\delta \geq (1 - \beta)^{-1}$.*

The proof of Proposition 3 is found in Appendix A. Following similar arguments to those used in the proof of Proposition 3, we calculate χ and η for any combination of the parameters $(\alpha, \beta, \delta, \gamma)$ in their specified parameter space. We collect results in Table 1. In the Supplementary Material, we only give details of the η calculations when $\alpha, \beta \in (0, 1)$, $\gamma > 0$ and $\delta = (1 - \beta)^{-1}$. For the other five cases in Table 1, we state results without proof. In particular, the argument underpinning the η calculation when $\delta > (1 - \beta)^{-1}$ is similar to the argument used when \bar{H} has a finite upper end point. In this case, $\eta = \alpha$ when $\alpha > 0$ and when $\alpha = 0$, η is not defined.

In Table 1, it is convenient to refer to $c = \max\{1, c_0\} \in [1, 1/\alpha]$ where $c_0 \in (0, 1/\alpha)$ satisfies

$$\gamma(1 - \alpha c_0)^{\delta - 1}(\delta - 1 + \alpha c_0) = c_0^\delta. \quad (13)$$

To give some intuition on the value of c , in Figure 2 we sketch the region of the parameter space corresponding to $c = 1$ (in red) for different values of γ . Finally in Figure 3 we visualise η for a set of different parameter combinations with $\delta = (1 - \beta)^{-1}$.

We note the following interesting findings. The parameter η is non-decreasing with increasing α and with increasing β . Parameter combinations $(\alpha, \beta, \gamma, \delta)$ exist for which $\alpha, \beta > 0$ but $\eta < 0.5$. Hence, there are cases for

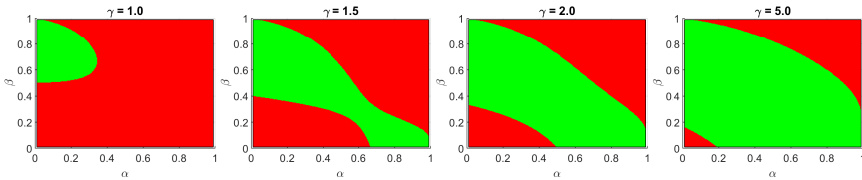


Figure 2 Visualisation of c_0 from equation (13) for $\gamma = 1, 1.5, 2, 5$ and $\delta = (1 - \beta)^{-1}$. The region corresponding to $c_0 \in (0, 1)$ is shown in red; the region corresponding to $c_0 \in (1, 1/\alpha)$ is shown in green.

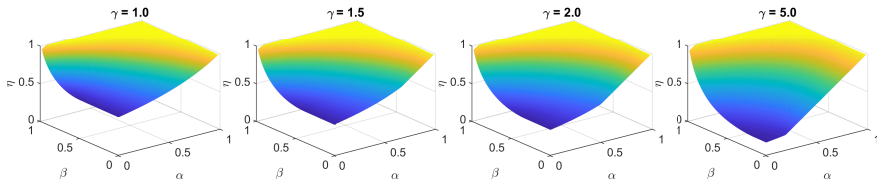


Figure 3 The value of η as a function of α, β and γ with $\delta = (1 - \beta)^{-1}$ from the HT model (11) and (12).

which Y increases with X but the extremes of (X, Y) are negatively associated as measured by η (Ledford and Tawn, 1996).

Finally we note that the Heffernan-Tawn model is not η invariant, i.e., there exist models that asymptotically follow the same conditional Heffernan-Tawn representation but have different η . We illustrate this result below with an example, but first we comment on its implications. Our finding implies that if X and Y are asymptotically independent, then there do not exist asymptotically consistent Heffernan-Tawn model-based estimators for probabilities $\mathbb{P}(Y > X > v)$ and $\mathbb{P}(X > v, Y > v)$ where v is large. This in turn provides an interesting insight in the lack of self-consistency of the Heffernan-Tawn model with regard to the choice of conditioning variable, see Liu and Tawn (2014).

To illustrate our claim, we consider two bivariate random variables (X, Y) and (X_{HT}, Y_{HT}) . Let (X, Y) follow an inverted bivariate extreme value distribution with a logistic dependence structure (Ledford and Tawn, 1996) on Laplace margins with parameter $\xi \in (0, 1]$, such that

$$\mathbb{P}(X > x, Y > y) = \exp \left\{ - \left[t_x^{1/\xi} + t_y^{1/\xi} \right]^\xi \right\}, \quad (14)$$

where $t_x := \log 2 - \log[2 - \exp(x)]$ for $x < 0$ and $t_x := \log 2 + x$ for $x > 0$, with t_y similarly defined. It is straightforward to derive that in the limit, the Heffernan-Tawn model (11) is applicable to (X, Y) with \bar{H} as in equation (12) and $o(z^\delta) = 0$. Specifically,

$$\lim_{x \rightarrow \infty} \mathbb{P}(YX^{\xi-1} > z \mid X = x) = \exp \left(-\xi z^{1/\xi} \right).$$

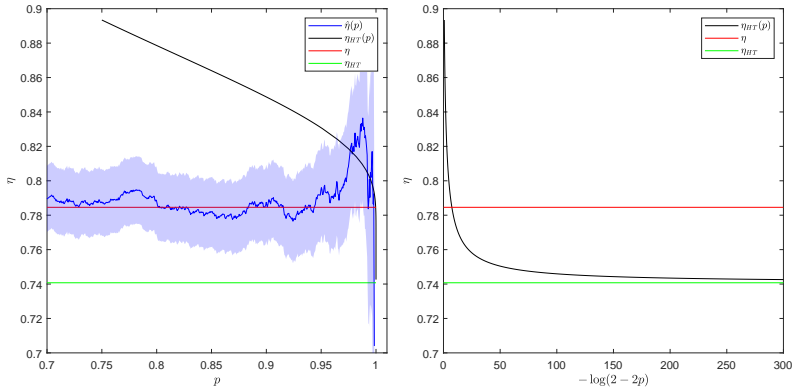


Figure 4 Coefficients of asymptotic independence η (red dashed) for distribution (14) with $\xi = 0.35$, and the corresponding value for the exact limiting HT model η_{HT} (green dashed), and its finite level counterpart $\eta_{HT}(p)$ (black dashed). Empirical estimates $\hat{\eta}(p)$ for a sample of size 10,000 with pointwise confidence intervals are shown in blue. Left and right hand panels are the same except for the scale of the x -axis, set on the right to illustrate the behaviour of $\eta_{HT}(p)$ for p near 1.

Now let (X_{HT}, Y_{HT}) be distributed following the exact version of the HT model associated with (X, Y) . That is, for $X_{HT} < u$, we have $(X_{HT}, Y_{HT}) = (X, Y)$, and for $X_{HT} \geq u$, $X_{HT} - u$ is a standard exponential and $Y_{HT} | X_{HT}$ follows model (11) with \bar{H} as in (12) with parameters $(\alpha, \beta, \gamma, \delta) = (0, 1 - \xi, \xi, 1/\xi)$ and $o(z^\delta) = 0$. In this case $\gamma < (1 - \beta)/\beta$, and Table 1 implies that the coefficient of asymptotic independence η_{HT} of (X_{HT}, Y_{HT}) is equal to $1/(\xi + 1)$. In contrast, it is straightforward to derive directly from definition (14) that η of (X, Y) is equal to $2^{-\xi}$. Hence $\eta_{HT} \neq \eta$ when $\xi \in (0, 1)$.

Finally we illustrate numerically the differences between η , η_{HT} and their finite level counterparts $\eta(p)$ and $\eta_{HT}(p)$ for $p \in (0, 1)$. For definiteness, we let (X, Y) follow distribution (14) with $\xi = 0.35$. We simulate a sample $\{(x_i, y_i) : i = 1, \dots, n\}$ of size $n = 10,000$. First we empirically estimate $\eta(p)$ from equation (3) for $p \in (0, 1)$ and calculate pointwise 95% confidence intervals using the binomial distribution. Next we note that $\eta(p) = \eta$ for $p \in (0.5, 1)$. Finally we calculate the corresponding $\eta_{HT}(p)$ for p near 1 using numerical integration.

Results are shown in Figure 4. Left and right hand plots are the same except for the scale of the x -axis, illustrating the behaviour of $\eta_{HT}(p)$ for p near 1. Reassuringly, the true η of the underlying model (red dashed) falls within the 95% confidence interval for its empirical counterpart $\hat{\eta}(p)$ (blue). Further, $\eta_{HT}(p)$ (black dashed) converges to η_{HT} (green dashed). We note that $\eta_{HT}(p)$ varies as a function of p and only seems to asymptote for $p > 1 - \exp(-50)/2 \approx 1 - 9.6 \cdot 10^{-23}$. Finally, since $\eta_{HT} < \eta$, we would expect that $\eta_{HT}(p)$ would underestimate η , but it turns out this is only the case for $p > 1 - \exp(-7.5)/2 \approx 0.9997$.

Supplementary information. In the Supplementary Material, we give the details of the mathematical derivations corresponding to the case studies.

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Appendix A Proofs

Proof of Proposition 2. We prove that for sufficiently large n , there exists a constant $C_1 > 0$ such that

$$\mathcal{I}_n := \int_I e^{g_n(x) - g_n(x_n^*)} dx \cdot \left(-g_n^{(k_0)}(x_n^*)\right)^{\frac{1}{k_0}} \geq C_1.$$

To bound \mathcal{I}_n from below, we first simplify its expression by applying the variable transformation $y = t_n(x) := (x - x_n^*) \left(-g_n^{(k_0)}(x_n^*)\right)^{1/k_0}$ and defining

$$h_n(y) := g_n \left(x_n^* + y \left(-g_n^{(k_0)}(x_n^*)\right)^{-\frac{1}{k_0}} \right), \text{ for } y \in I'_n := \{t_n(x) : x \in I\}.$$

Then, the integral \mathcal{I}_n becomes

$$\mathcal{I}_n = \int_{I'_n} e^{h_n(y) - h_n(0)} dy.$$

We note that for all $n \in \mathbb{N}$, we have $0 \in I'_n$, $h_n \in C^{k_0}(I'_n)$, and $h_n(0) > h_n(y)$ for all $y \in I'_n \setminus \{0\}$. Moreover, we have for $y \in I'_n$, $i = 1, \dots, k_0$,

$$h_n^{(i)}(y) = g_n^{(i)} \left(x_n^* + y \left(-g_n^{(k_0)}(x_n^*)\right)^{-1/k_0} \right) \cdot \left(-g_n^{(k_0)}(x_n^*)\right)^{-i/k_0}.$$

Hence, $h_n^{(k_0)}(0) = -1$ and $\lim_{n \rightarrow \infty} h_n^{(i)}(0) = 0$ for all $1 \leq i < k_0$. Using Taylor's theorem, there exists a function $\xi(y)$ taking on a value between 0 and y such that

$$h_n(y) - h_n(0) = \sum_{i=1}^{k_0-1} \frac{y^i}{i!} h_n^{(i)}(0) + \frac{y^{k_0}}{k_0!} h_n^{(k_0)}(\xi(y)).$$

Let $\tilde{\varepsilon} > 0$. Because $\lim_{n \rightarrow \infty} h_n^{(i)}(0) = 0$ for all $i < k_0$, we can find an $N_0 \in \mathbb{N}$ such that for all $n > N_0$, we have $\max_{i=1, \dots, k_0-1} |h_n^{(i)}(0)| < \tilde{\varepsilon}$. Moreover, from the assumptions of the proposition, we can find a $\delta > 0$ and associated $\varepsilon > 0$ and $N_1 \in \mathbb{N}$ such that for all $n > N_1$, $h_n^{(k_0)}(y) > -(1 + \varepsilon)$ for $y \in (-\delta, \delta) \cap I'_n$. For $n > \max\{N_0, N_1\}$,

$$h_n(y) - h_n(0) > -|y|\tilde{\varepsilon} - \frac{|y|^2}{2!}\tilde{\varepsilon} - \dots - \frac{|y|^{k_0-1}}{(k_0-1)!}\tilde{\varepsilon} - \frac{(1+\varepsilon)|y|^{k_0}}{k_0!} > -\tilde{\varepsilon}e^\delta - \frac{(1+\varepsilon)|y|^{k_0}}{k_0!}$$

for $y \in (-\delta, \delta) \cap I'_n$. Hence, we derive a lower bound

$$\mathcal{J}_n \geq e^{-\bar{\varepsilon}e^\delta} \int_{I'_n \cap (-\delta, \delta)} e^{-\frac{(1+\varepsilon)|y|^{k_0}}{k_0!}} dy =: C_1.$$

From the connectedness of I and $0 \in I'_n$, we conclude that $I'_n \cap (-\delta, \delta)$ has positive mass under the Lebesgue measure. Hence, $C_1 \in (0, \infty)$. \square

Proof of Proposition 3. Let (X, Y) be a random vector such that X and Y both have standard Laplace margins. Moreover, assume that there exist $-1 \leq \alpha \leq 1$, $0 \leq \beta < 1$ and $u > 0$ such that for $x > u$

$$\mathbb{P}(Y > y \mid X = x) = \bar{H} \left(\frac{y - \alpha x}{x^\beta} \right)$$

holds for all $y \in \mathbb{R}$ with

$$\bar{H}(z) = \exp(-\gamma z^\delta) \mathbb{1}\{z > 0\} + \mathbb{1}\{z \leq 0\},$$

where $\gamma, \delta > 0$. Now, let Z be a random variable that is independent of X and have survival function \bar{H} . We derive that $\delta \geq (1 - \beta)^{-1}$ must hold. Since Y is distributed as a standard Laplace, we have for $y > 0$

$$\begin{aligned} \frac{\exp(-y)}{2} &= \mathbb{P}(\alpha X + X^\beta Z \geq y, X \geq u) + \mathbb{P}(Y \geq y, X < u) \\ &\geq \mathbb{P}(\alpha X + X^\beta Z \geq y, X \geq u) \geq \mathbb{P}(X^\beta Z \geq y, X \geq u) \\ &= \int_u^\infty \mathbb{P}\left(Z \geq \frac{y}{x^\beta}\right) f_X(x) dx = \frac{1}{2} \int_u^\infty \exp\left(-\frac{\gamma y^\delta}{x^{\beta\delta}} - x\right) dx =: \tilde{\mathcal{J}}_y. \end{aligned}$$

We will show that $2 \exp(y) \tilde{\mathcal{J}}_y > 1$ for sufficiently large y , if $\delta < (1 - \beta)^{-1}$, which thus would contradict with the marginal distribution of Y . This result holds trivially for $\beta = 0$. So, for now, we let $\beta > 0$. We will prove this asymptotic inequality by applying Proposition 2, with $k_0 = 2$, to bound $\tilde{\mathcal{J}}_y$ from below.

First define $I := [u, \infty)$ as the integration domain, and

$$g_y(x) := \exp\left(-\frac{\gamma y^\delta}{x^{\beta\delta}} - x\right) \mathbb{1}\{x \in I\}, \quad \text{and} \quad h_y(x) := \left(-\frac{\gamma y^\delta}{x^{\beta\delta}} - x\right) \mathbb{1}\{x \in I\}.$$

Next we find the mode x_y^* of $g_y(x)$. We assume that x_y^* lies in the interior of I such that $h'_y(x_y^*) = 0$, which implies that $\beta\delta\gamma y^\delta (x_y^*)^{-\beta\delta-1} = 1$. So, $x_y^* = (\beta\delta\gamma)^{\frac{1}{\beta\delta+1}} y^{\frac{\delta}{\beta\delta+1}}$, which lies in the interior of I for sufficiently large y . We now compute

$$g_y(x_y^*) = \exp\left(-\frac{\gamma y^\delta}{(x_y^*)^{\beta\delta}} - x_y^*\right) = \exp\left(-Ay^{\frac{\delta}{\beta\delta+1}}\right)$$

with $A := \gamma(\beta\delta\gamma)^{-\frac{\beta\delta}{\beta\delta+1}} + (\beta\delta\gamma)^{\frac{1}{\beta\delta+1}}$. Secondly,

$$h_y''(x_y^*) = -\beta\delta(\beta\delta+1)(x_y^*)^{-\beta\delta-2}\gamma y^\delta = -(\beta\delta+1)(\beta\delta\gamma)^{-\frac{1}{\beta\delta+1}} y^{-\frac{\delta}{\beta\delta+1}}.$$

Using these expression, we can now check that the assumptions from Proposition 2 with $k_0 = 2$ are satisfied. First we note that $h_y'(x_y^*)(-h_y''(x_y^*))^{-1/2} = 0$. Next let $C > 0$ and $|x| \leq C$, then

$$\begin{aligned} & \lim_{y \rightarrow \infty} \frac{h_y''\left(x_y^* + \frac{x}{\sqrt{-h_y''(x_y^*)}}\right)}{h_y''(x_y^*)} \\ &= \lim_{y \rightarrow \infty} \frac{-\beta\delta(\beta\delta+1) \left((\beta\delta\gamma)^{\frac{1}{\beta\delta+1}} y^{\frac{\delta}{\beta\delta+1}} + \frac{x}{\sqrt{(\beta\delta+1)(\beta\delta\gamma)^{-\frac{1}{\beta\delta+1}} y^{-\frac{\delta}{\beta\delta+1}}}} \right)^{-\beta\delta-2}}{-(\beta\delta+1)(\beta\delta\gamma)^{-\frac{1}{\beta\delta+1}} y^{-\frac{\delta}{\beta\delta+1}}} \gamma y^\delta \\ &= \lim_{y \rightarrow \infty} \frac{\left(y^{\frac{\delta}{\beta\delta+1}} + \frac{x}{\sqrt{(\beta\delta+1)(\beta\delta\gamma)^{\frac{1}{\beta\delta+1}} y^{-\frac{\delta}{\beta\delta+1}}}} \right)^{-\beta\delta-2}}{y^{-\frac{\delta}{\beta\delta+1}}} y^\delta \\ &= \lim_{y \rightarrow \infty} \left(1 + \frac{x}{\sqrt{(\beta\delta+1)(\beta\delta\gamma)^{\frac{1}{\beta\delta+1}} y^{\frac{\delta}{\beta\delta+1}}}} \right)^{-\beta\delta-2} \\ &= 1, \end{aligned}$$

which is sufficient to show that for each \tilde{x} , Proposition 2 is applicable with $k_0 = 2$ on interval $I_{\tilde{x}} := \left[x_y^* - \frac{\tilde{x}}{\sqrt{-h_y''(x_y^*)}}, x_y^* + \frac{\tilde{x}}{\sqrt{-h_y''(x_y^*)}} \right]$. Hence for each \tilde{x} , there exists a constant $C_1(\tilde{x}) > 0$ such that for sufficiently large y ,

$$\begin{aligned} y^{-\frac{\delta/2}{\beta\delta+1}} \exp\left(Ay^{\frac{\delta}{\beta\delta+1}}\right) \cdot \tilde{\mathcal{J}}_y &\geq y^{-\frac{\delta/2}{\beta\delta+1}} \exp\left(Ay^{\frac{\delta}{\beta\delta+1}}\right) \cdot \int_{I_{\tilde{x}}} g_y(x) dx \\ &= \frac{C_1(\tilde{x})(\beta\delta\gamma)^{\frac{1}{2(\beta\delta+1)}}}{\sqrt{\beta\delta+1}}. \end{aligned}$$

Using the inequality $2\exp(y)\tilde{\mathcal{J}}_y \leq 1$, we must have

$$y^{-\frac{\delta/2}{\beta\delta+1}} \exp\left(Ay^{\frac{\delta}{\beta\delta+1}}\right) \cdot \frac{1}{2} \exp(-y) \geq \frac{C_1(\tilde{x})(\beta\delta\gamma)^{\frac{1}{2(\beta\delta+1)}}}{\sqrt{\beta\delta+1}} \quad (\text{A1})$$

for sufficiently large y . Since $0 \leq \beta < 1$, we note that if $\delta < (1-\beta)^{-1}$ then inequality (A1) does not hold. So, we derive that $\delta \geq (1-\beta)^{-1}$. \square

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