



# Bayesian covariate models in extreme value analysis

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# Acknowledgement

- Kevin Ewans, Graham Feld and other Shell colleagues.
- Colleagues in academia, especially at Lancaster University.

# Hurricane Katrina



# Hurricane Katrina



# Motivation: extremes in met-ocean

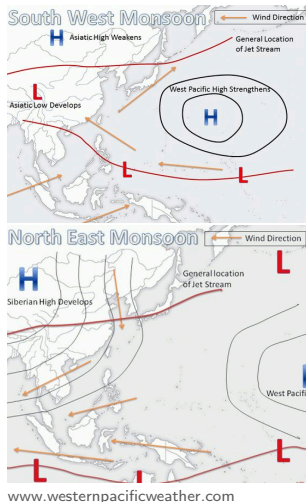
- **Rational** and **consistent** design an assessment of **marine structures**
  - Reduce bias and uncertainty in estimation of **return values**.
- Non-stationary **marginal** and **conditional** extremes
  - Multiple locations, multiple variables, time-series,
  - **Multidimensional** covariates.
- Improved **understanding** and **communication** of risk
  - Incorporation within **well-established** engineering design practices,
  - **“Knock-on” effects** of “improved” inference,
  - New and existing structures.

# Marginal directional-seasonal extremes

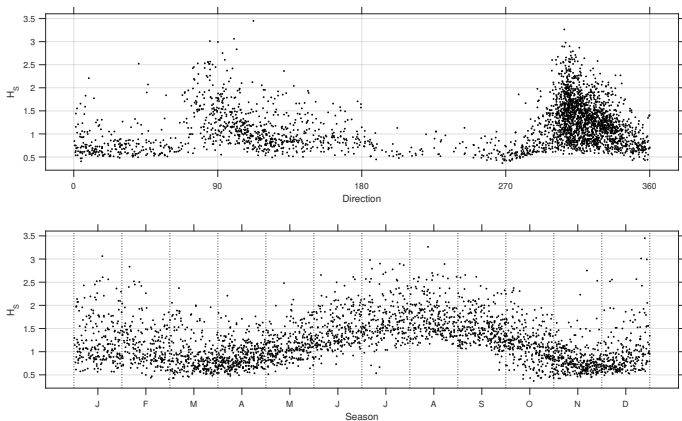


# Marginal directional-seasonal extremes

- Marginal model: **single** location.
- Response: **storm peak significant wave height,  $H_S^{sp}$** .
- Wave climate: **monsoonal**.
- Southwest monsoon ( $\sim$  August, to northwest).
- Northeast monsoon ( $\sim$  January, to east-northeast).
- Long **fetches** to Makassar Strait, Java Sea.
- Land shadows of Borneo (northwest), Sulawesi (northeast), Java (south).



# Directional and seasonal variability



**Figure:** Hindcast storm peak significant wave height  $H_s^{SP}$  for 1956 – 2012 (black) on direction  $\theta$  (upper panel, to which waves propagate) and season  $\phi$  (lower panel). Also shown is sea-state significant wave height  $H_s$  (grey) on direction  $\theta$  (upper panel) and season  $\phi$  (lower panel). Northeast monsoon: August to northwest (315). Southwest monsoon: January to east-northeast (110).



# Storm model

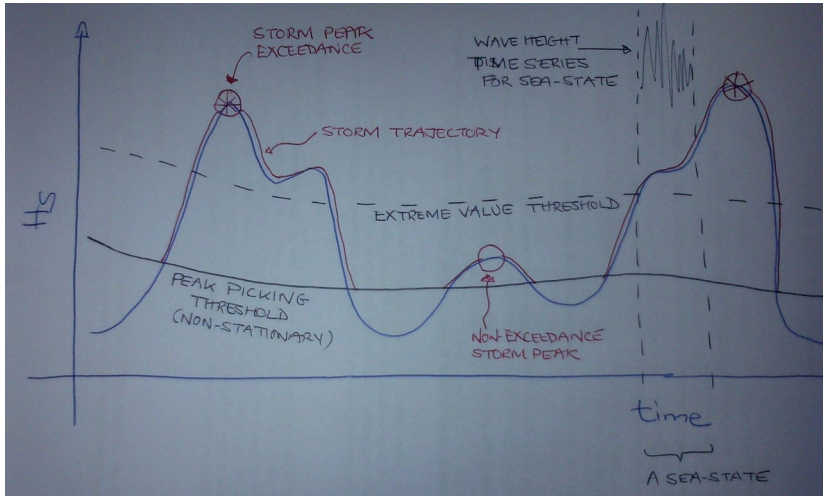


Figure:  $H_s \approx 4 \times$  standard deviation of ocean surface profile at a location corresponding to a specified period (typically three hours)

# Model components

- Linear wave theory suggests ocean waves Rayleigh distributed, Longuet-Higgins [1952].
- Response  $y$  not exceeding the extreme value threshold  $\psi$  follows a truncated Weibull distribution with density similar to Frigessi et al. [2002]

$$f(y|\xi, \sigma, \alpha, \gamma, \psi, \tau) = \begin{cases} \tau \times f_{TW}(y|\alpha, \gamma) & \text{for } y \leq \psi \\ (1 - \tau) \times f_{GP}(y|\xi, \sigma) & \text{for } y > \psi \end{cases}$$

- $\psi$  is defined by  $\tau$ ,  $\alpha$  and  $\gamma$

$$\psi|\tau, \alpha, \gamma = \alpha (-\log(1 - \tau))^\gamma .$$

- No imposition of continuity in the density.
- Rate of occurrence  $\rho|r$  is modelled as a Poisson distribution as in Chavez-Demoulin and Davison [2005], where  $r$  is observation counts in covariate bins.

# Bayesian P-Splines

- Physical considerations suggest model parameters  $\alpha, \gamma, \rho, \xi$  and  $\sigma$  vary smoothly with covariates  $\theta, \phi$
- Values of  $(\eta =) \alpha, \gamma, \rho, \xi$  and  $\sigma$  all take the form

$$\eta = B\beta_\eta$$

## Priors:

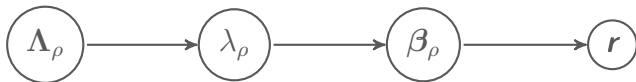
$$\beta_\eta \sim \lambda \exp\left(-\frac{1}{2}\beta_\eta' D' D \beta_\eta\right)$$

$$\lambda \sim \text{Gamma}(\Lambda_\eta)$$

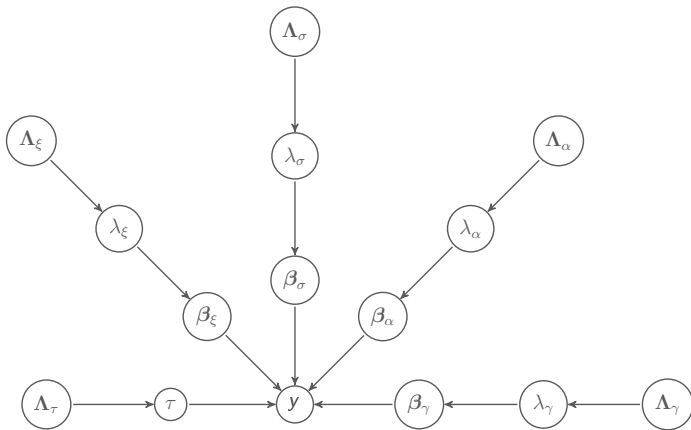
$$\tau \sim \text{Beta}(\Lambda_\tau)$$

- $B$  is a spline basis and  $D$  is a difference matrix of order  $k$ .
- Smoothnesses  $\lambda$  can be estimated very easily using Gibbs sampling see Brezger and Lang [2006].
- $\Lambda_\eta$  are smoothness hyper-parameters giving diffuse prior.

# DAG for Poisson Rate of Occurrence

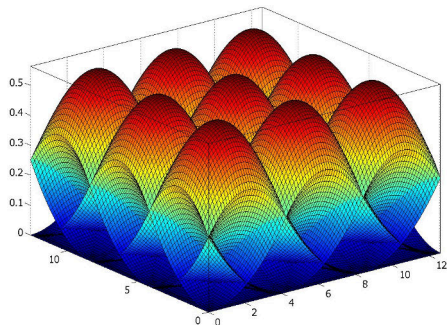
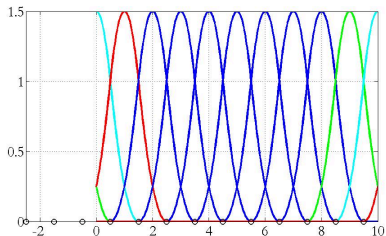


# DAG for Weibull GP



# Penalised B-splines

- **Wrapped** bases for periodic covariates (direction, season).
- **Multidimensional** bases easily constructed using tensor products, Eilers and Marx [2010].
- **GLAMs**, Currie et al. [2006] for efficient computation in high dimensions.



# Sampling for P-Splines

- Cannot write full conditionals for generalised Pareto likelihood, so no Gibbs sampling; simple Metropolis Hastings methods don't mix well.
- Neighbouring spline parameters are highly correlated due to smoothness prior.
- Correlated spline proposals made from

$$\beta^* \sim N(\beta, G^{-1})$$

where

$$G = B'B + \lambda D'D .$$

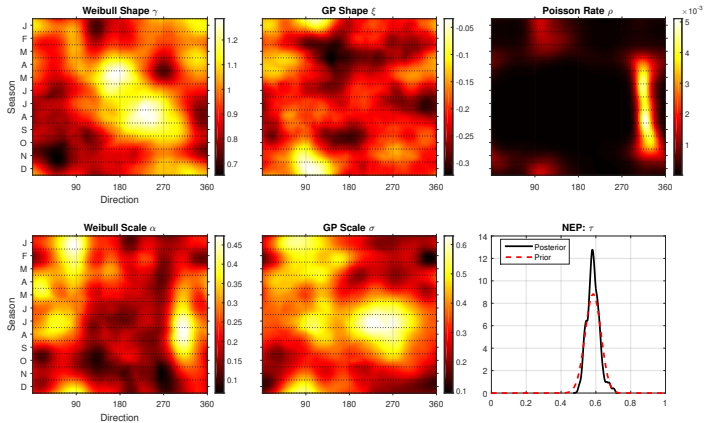
- Gradient based MCMC methods also help to improve mixing.

# MCMC proposals exploiting gradient

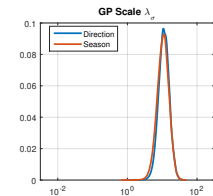
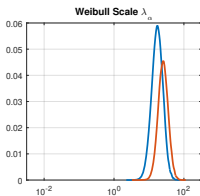
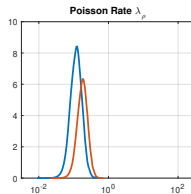
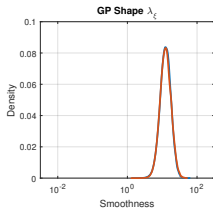
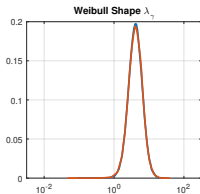
- Simple Metropolis Hastings sampling is a “stochastic analogue” of penalised likelihood optimisation, but does not exploit gradient information.
- MALA and mMALA use gradient information for MCMC proposal generation. These are stochastic analogues of back-fitting and IRLS, see Roberts and Stramer [2002]. They provide random walks *downhill*, particularly important with high numbers of correlated parameters.



# Parameter plots



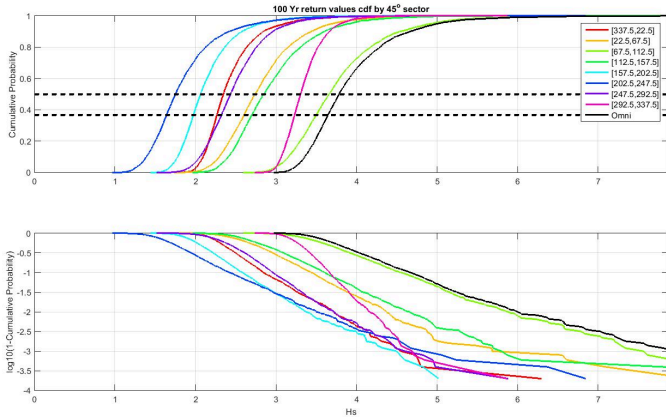
# Smoothness



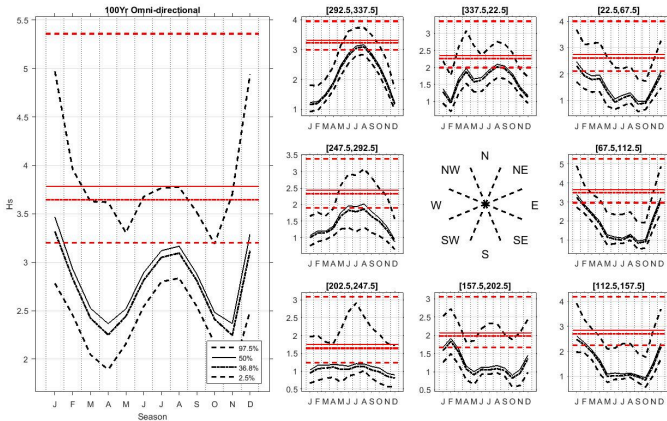
# Return values

- Estimated by simulation from sample of posterior.
- $H_{S100}$  is the maximum value of  $H_S^{SP}$  in a simulation period of 100-years.

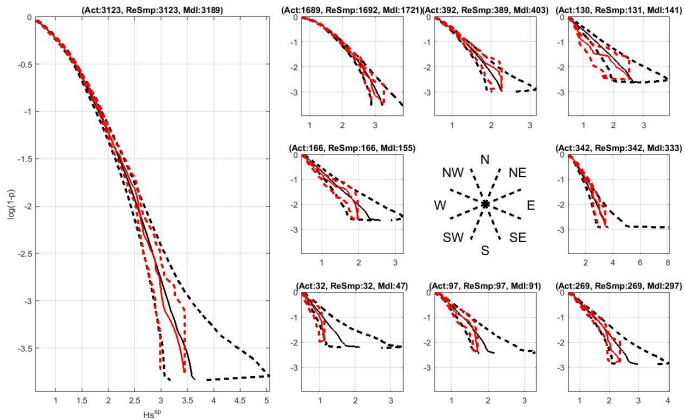
# Directional 100yr return values



# Directional seasonal 100yr return values



# Directional Seasonal 100Yr Return Values



# Summary

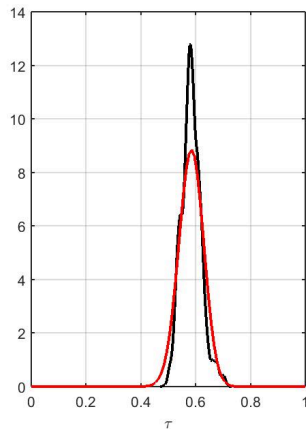
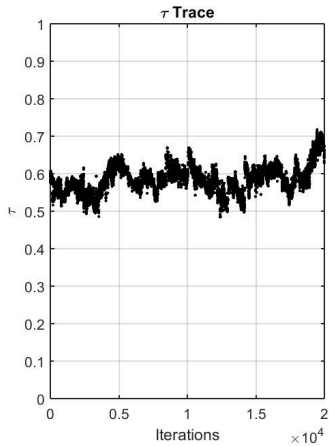
- Modelling non-stationarity essential for understanding extremes and development of design conditions.
- Non-parametric covariate models flexible, but need to estimate roughness.
- P-splines simple to implement and extend to periodic and higher dimensional domains.
- Bayesian P-spline for extremes
  - Roughness estimated using Gibbs sampling,
  - Different roughness for each covariate dimension,
  - Correlated MCMC proposals exploiting gradient,
  - Computationally efficient, and generally more stable than optimisation to point solution.

# References

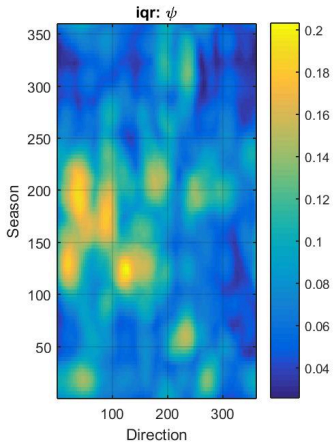
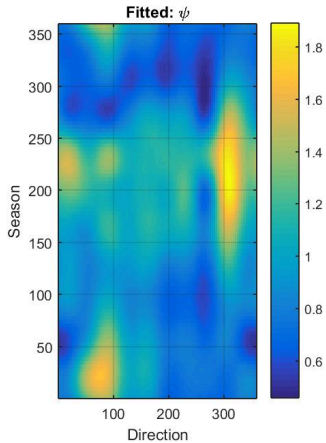
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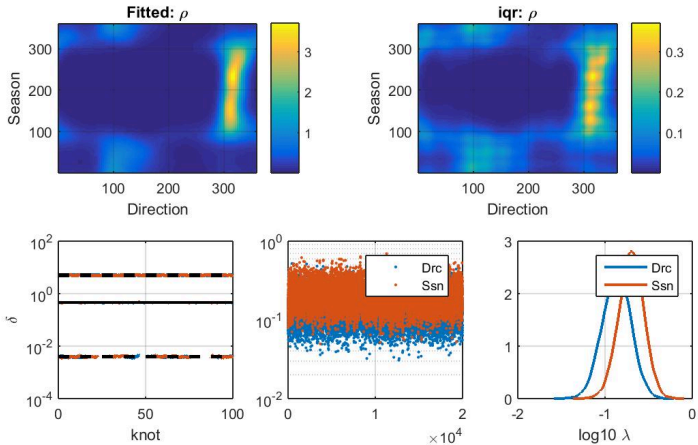
# Parameters $\tau$



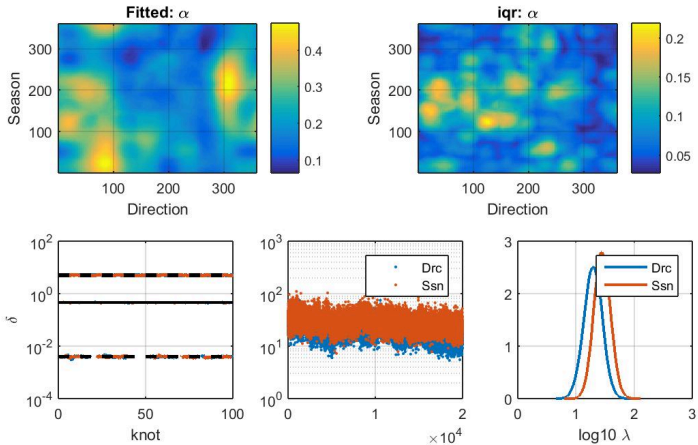
# Parameters $\psi$



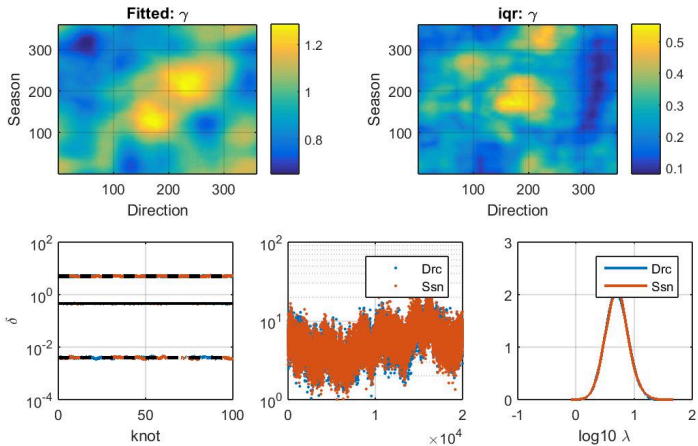
# Parameters $\rho$



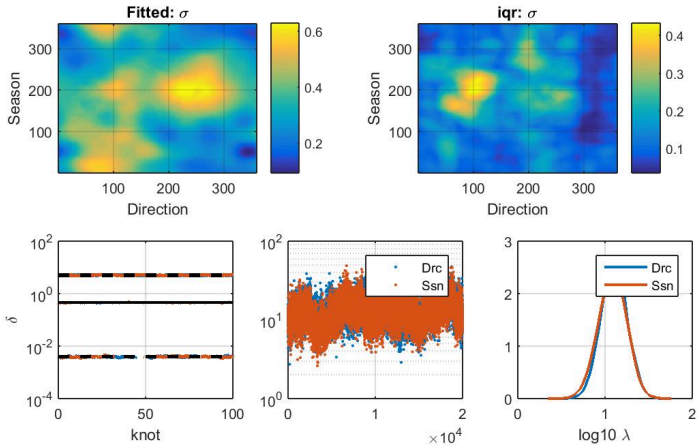
# Parameters $\alpha$



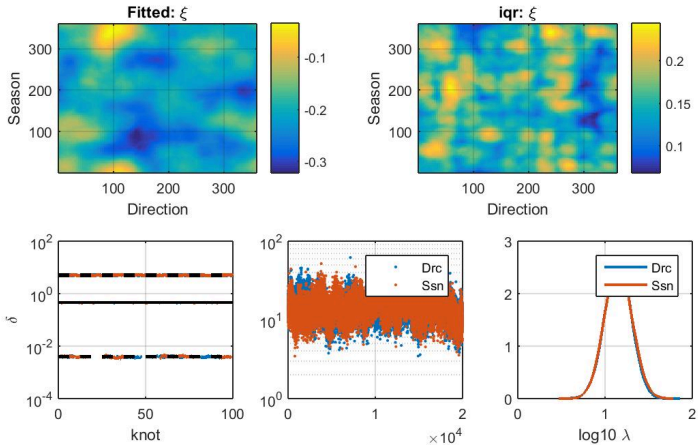
# Parameters $\gamma$



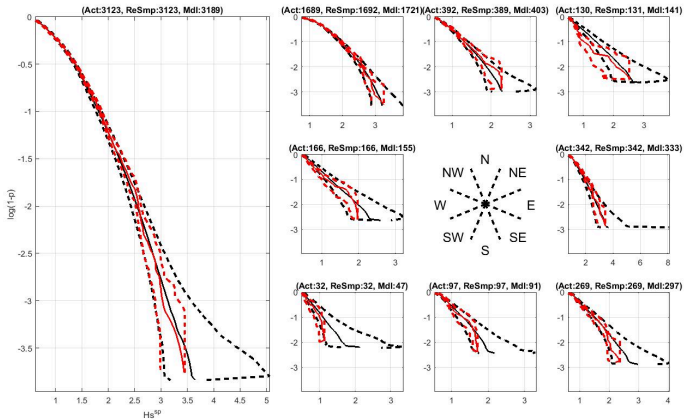
# Parameters $\sigma$



# Parameters $\xi$



# Directional Seasonal 100Yr Return Values





# Gradient Based MCMC

- **HMC**: Hamiltonian Monte Carlo: uses first derivatives of parameters have momentum based on gradient. This approach can be unstable so several leapfrog steps are taken instead of single step.
- **Riemann manifold HMC**: uses second derivatives of parameters. Here 2 leapfrog steps are needed so this is computationally challenging
- **MALA** Metropolis adjusted Langevin algorithm: uses first derivatives steps. Proposal calculated  $\alpha^*$  by sampling from a Normal distribution  $N(\mu, \Sigma)$  where

$$\begin{aligned}\mu &= \alpha - \frac{\epsilon}{2} \frac{\partial}{\partial \alpha} (L + L_{prior}) \\ \Sigma &= \epsilon I\end{aligned}\tag{1}$$

and then implement standard MH based on this proposal.

- Given a current state  $\alpha$  a proposal  $\alpha^*$  is sampled from  $N(\mu(\alpha), \Sigma)$ , where

$$\begin{aligned}\mu(\alpha) &= \alpha - \frac{\epsilon}{2} G^{-1}(\alpha) \frac{\partial}{\partial \alpha} (L + L_{prior}) \\ \Sigma &= \epsilon G^{-1}(\alpha)\end{aligned}\tag{2}$$

and then MH is carried through as before. As in MALA we again do not have symmetric proposals and so we must calculate the full acceptance probability.

- it is also interesting to notice the similarities between IWLS and mMALA. To see this compare

$$G(\alpha_\xi)^{-1} = (B' \frac{\partial^2 L}{\partial \xi^2} B + \lambda_\xi P)^{-1}\tag{3}$$

$$\hat{\alpha}_{t+1} = (B' \hat{W}_t B + \lambda D' D)^{-1} B' \hat{W}_t \hat{z}_t\tag{4}$$